

IR Polarimetric CamCorder and Representative Imagery

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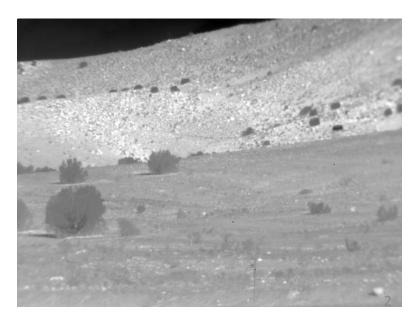


Baseline Technology

- Conventional EO/IR sensor suites
- Situations with poor viewing and low contrast of targets and backgrounds
- Targets in background often undetected
- Target contrast reverses sign









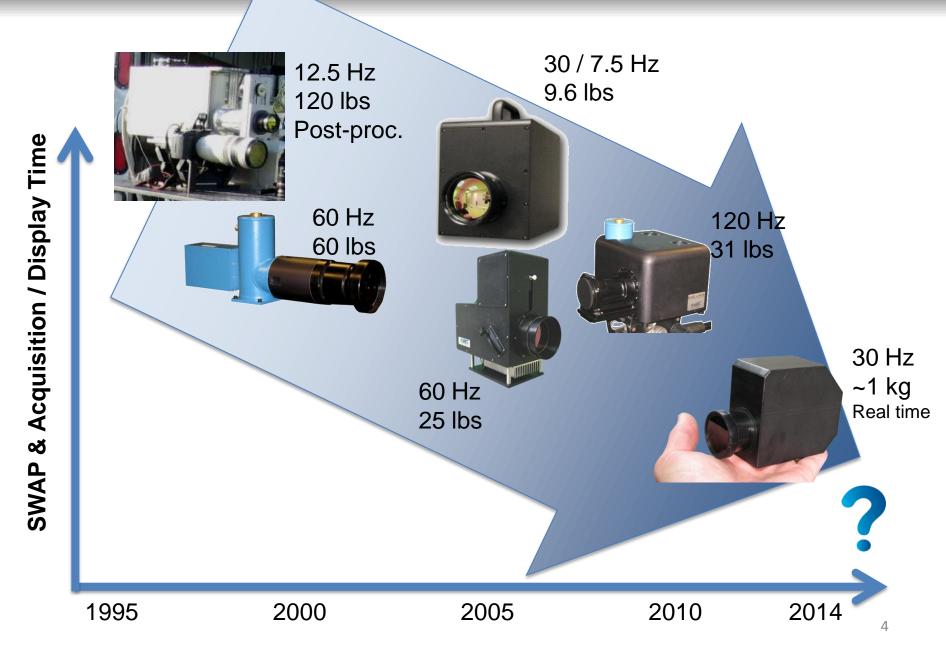
Problem Statement

Improve Performance of EO / IR Optical Sensors

- Terrestrial targets
 - Enhanced target detection
 - Improve target detection range
 - Reduce clutter
- Marine targets
 - Small vessel threat detection (zodiac, sport craft, semi-submersible)
 - Surface swimmer detection and discrimination
 - Collision avoidance
 - High traffic areas (ports, straits)
- Airborne targets
 - Enhanced target detection
 - Improve target detection range
 - Collision avoidance



Sensor Progress

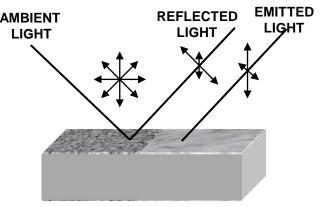




Optical Polarization

- Polarization results from vector nature of light
- Fundamental quantity along with intensity and wavelength
- Same physics we exploit with polarized glasses except multi-mode detection gives quantitative results
- Polarization present in UV, Vis, SWIR, MWIR, and LWIR
- IR polarization signals result from preferential emission of polarized light
- Polarization depends strongly on
 - angle of incidence and surface properties
 - The greater the angle of incidence, the greater the signal
 - The rougher the surface, the smaller the signal
- Manmade objects have significantly different polarization signature from natural backgrounds





- Measurement of polarization adds contrast
- Polarization contrast does not require thermal (conventional) contrast
- Polarized and conventional imagery are collected at the same time



Multi-Mode Imaging

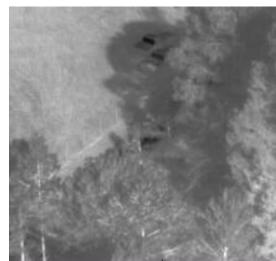
- Polarization Enhances Contrast
- Man-made objects tend to be polarized, natural backgrounds are unpolarized
- Polarization contrast is often present even when there is no conventional (thermal) contrast
- Polarimeter measures both => Multi-mode Imaging

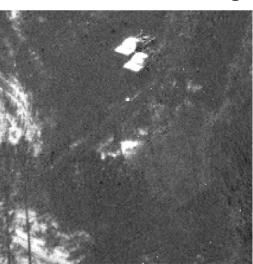
Visible Camera Image

IR Image

IR Polarization Image









Multi-Mode Imaging





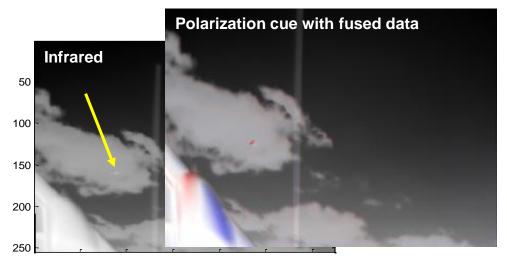


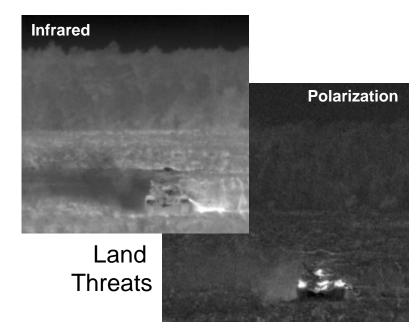




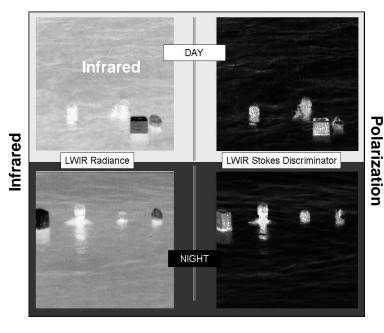
Mission Areas

Air Threats





Waterborne Threats

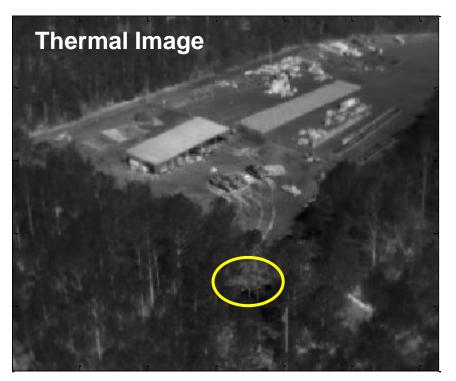


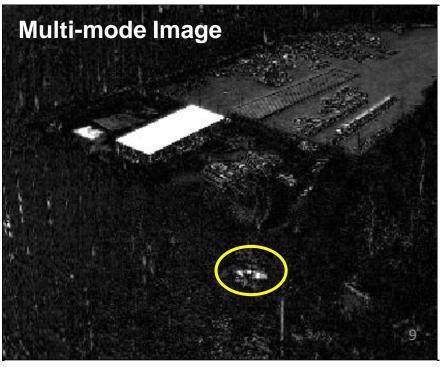
- Sensor hardware choices depend on typical targets, nature of platform, SWAP requirements
- Spectrum choice depends on mission requirements, environment, and day / night



Multi-mode Detection of Obscured Targets



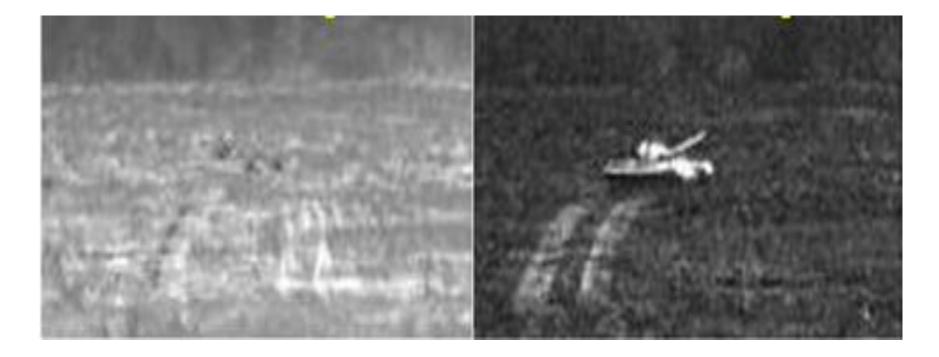






Acquire And Track Differently.

Detect Manmade Objects In Low Contrast Scenes.



Traditional Night Vision Imagery (Long Wave Infrared. Outdoors) Polaris Night Vision Imagery (Long Wave Infrared. Outdoors)



Polaris Spyder IR Polarimetric Camcorder

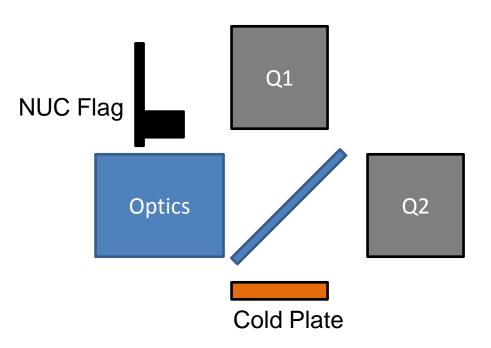
A sensor for contrast enhancement

- Real-time IR Polarimetric Video
- Spyder enhances contrast compared to standard thermal imagery, even with no thermal contrast
- Improves detection by up to 30 times
- Additive / simultaneous capability; adds to thermal imagery
- Day / night real-time video
- Small size, weight (2.5 lbs), and power sensor is compatible with unmanned platforms, video output compatible existing video data links



Polaris Spyder Ursa IR Imaging Polarimeter

- Division of Amplitude Configuration
- Uses two FLIR Tau uncooled microbolometers
- Integrated electronics computes realtime S₀ and S₁
- Scales image and outputs analog video to display or DVR



- Optics optimized to compensate for beam splitter loss
- Integrated NUC
- Cold plate monitored for temperature stabilization
- Two FPAs are co-registered mechanically & in software

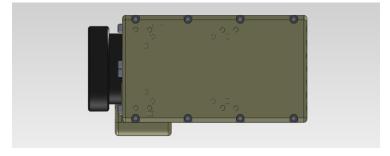
Spyder Specifications

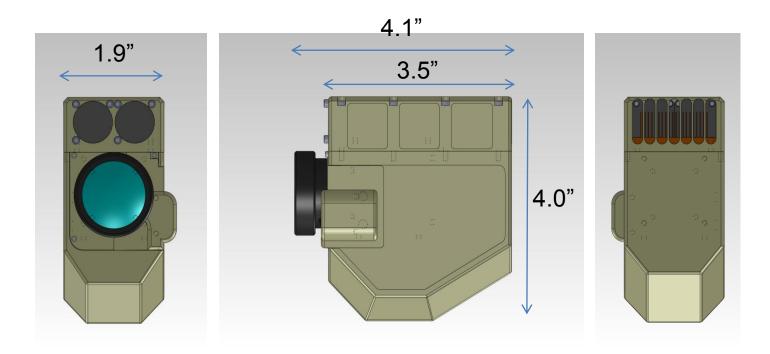


Spectral Band7 – 13 micronsPolarizationTwo orthogonal linear polarizationsOutput modesS ₀ or S ₁ of Stokes vector, alternating S ₀ and S ₁ Frame rate30 HzOutput formatNTSC videoFormat320 x 256F/#F/0.9Horizontal Field of View30°Run time: 8 Li ion AA batteries Power draw1 1/2 hours 6 W typ.Weight of optical head of user interface<1.25 lbs.			The state and the second states and
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Sensor Assembly





Weight ≈ 0.5 kilo gram



Operation

- Power switch on processor box
- Cycling through modes by pushing thumb button Modes are S0 and S1 and Auto-swap (swapping between S0 and S1)
- Perform 1 point NUC by pressing Button 1 (top bottom). This button doesn't work if pressed within 10 seconds of pushing Button 2.
- Perform 2 point NUC by pressing Button 2 (middle bottom)
- Cycle through scale modes by pressing Button 3. Scale 0 is auto-scale. Scales 1, 2, and 3 adjusts brightness / contrast.



Hands Free Operation

- Hands free or camcorder-style hand held system ready for use
- Industrial monitoring
- Situational Awareness
- Object detection in clutter
- Transportation safety

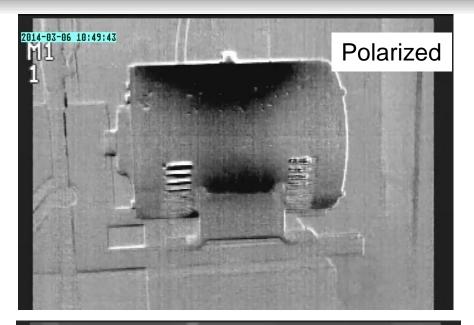


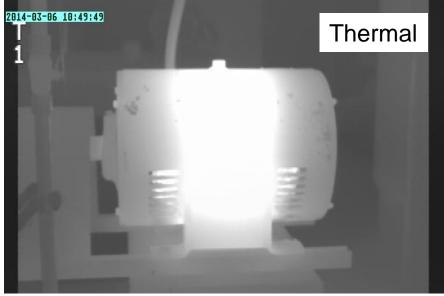




Spyder Imagery







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Spyder Imagery









Summary

- Polarization advantages
- Multi-mode sensor often enhances detection of difficult targets
- Contrast is improved through suppression of background, no contrast reversals
- Signatures are frequently more robust than conventional imagery with time of day
- Conventional imagery is collected simultaneously and is precisely registered
- IR Polarimetric Camcorder
- First hand held / hands free IR Imaging Polarimeter
- Small size, weight, power requirements enables
 - Discovery
 - Variety of platforms
 - New missions
 - Generate acceptance of new technology